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**IRT Eurocard**  
**Type DDC-3471**  
**SPI to SPI, ASI**  
**MPEG Transport Stream Adapter**

**Designed and manufactured in Australia**

**IRT can be found on the Internet at:**  
**<http://www.irtelectronics.com>**

**IRT Eurocard  
Type DDC-3471  
SPI to SPI, ASI  
MPEG Transport Stream Adapter  
Instruction Book**

Table of Contents

Section	Page
General description	3
Application	4
Block diagram	4
Technical specifications	5
Technical description	6
Configuration	7
Links & options	7
Installation	8
Operational safety	8
Pre-installation	8
Installation in frame or chassis:	8
Connections:	9
Front & rear panel connector diagrams	9
Operation	10
Front indicators	10
Processing controls	10
Maintenance & storage	11
Warranty & service	11
Equipment return	11
Characteristics of signal types	12
Coding characteristics	12
G.703	12
Synchronous Parallel Interface	12
Asynchronous Serial Interface	13
MPEG-2 transport layer coding	14
Electrical characteristics	16
G.703	16
SPI	17
ASI	17
References	18
Glossary of terms	19
Drawing index	20

## General description

The DDC-34XX series forms a family of data transcoders for converting between the commonly used MPEG2 Transport Stream formats by the broadcast industry for video distribution.

The series is a development of the previous 3200 series modules incorporating changes for EMC compliance and simplification of product coding to cover the various fixed G.703 data rates.

MPEG2 propounded a method of data encoding without defining the physical transport layer. This was left to the manufacturers to decide, with the result that a number of proprietary systems emerged with incompatible electrical characteristics. Whilst some of these have quickly disappeared, there remain reasons for using particular systems for some purposes.

Commonly used formats include:

- SPI (Synchronous Parallel Interface MPEG2)

- Unframed G.703 at 2, 8, 34 & 45 Mb/s

- ASI-C (Asynchronous Serial Interface 270 Mb/s Coaxial cable)

- ASI-O (Asynchronous Serial Interface 270 Mb/s Fibre optic cable)

In an effort to standardise, the DVB has recommended the use of the ASI format where possible.

However, it is often convenient to use Telecom data networks for transport. These generally use G.703 formats at particular fixed rates.

Test instrument manufacturers, on the other hand, often prefer the use of SPI format, due to its lower processing speed requirements.

The ASI-O interface is of limited usefulness, due to the specification of multimode fibre with only a short haul capability. Optical transport of ASI can be better achieved by the use of IRT's DVT/DVR-3210 single mode SDI/ASI fibre optic link, which has a capability of transporting ASI signals more than 50 Km.

IRT's 34XX series of adapters provide a modular approach to connecting between the different transport types.

The 34XX series find particular application in CATV Headends where equipment from different manufacturers uses different formats. They may also be used for monitoring connections to test equipment.

In addition, the DDC-3471 provides facilities for changing certain coding features of the MPEG transport stream to ensure compatibility between signals.

**Product Selection Chart**

Product	Data rates	Input	Outputs	
DDC-3460	/34	G.703-E3	ASI	
	/45	G.703-DS-3	ASI	
DDC-3471	2 to 60 Mb/s	SPI	SPI	ASI
DDC-3480	/34	ASI	G.703-E3	
	/45	ASI	G.703-DS-3	
DDC-3330	1.5 to 50 Mb/s	ASI	SPI	
DDC-3340	1.5 to 50 Mb/s	SPI	ASI	
MFC-3465	/34	G.703-E3	ASI	
	/45	G.703-DS-3	ASI	
MFC-3485	/34	ASI 1.5 to 30 Mb/s	SPI	G.703-E3
	/45	ASI 1.5 to 39 Mb/s	SPI	G.703-DS-3

Note: The DDC-3471 allows Reed Solomon correction and the insertion or removal of interleaving and MPEG2 transport stream spectrum shaping randomisation. This makes it an ideal adjunct to test equipment or for matching signal from various sources using different encoding options.

## Applications:

- **Block length indication and error detection.**
- **Interface to test equipment.**
- **Interfacing to Telecoms switched data network.**
- **Interfacing various MPEG2 TS formats.**
- **Interleaving or de-interleaving. \***
- **Reed Solomon insertion & correction. \***
- **Spectrum dispersion correction. \***
- **Signal monitoring for remote alarm indications.**

\* DDC-3471 only.

## Application

Processes which may be performed by the DDC-3471 are:

### Baseband interfacing and sync

This unit adapts the data structure to the format of the signal source. This may be a DDC-3460 or simply the input interface of the DDC-3471. The framing structure is in accordance with MPEG-2 transport layer including sync Bytes.

### Sync 1 inversion and randomisation (Scrambling)

The Sync 1 Byte is inverted according to the MPEG-2 framing structure, and the data stream randomised for spectrum shaping purposes.

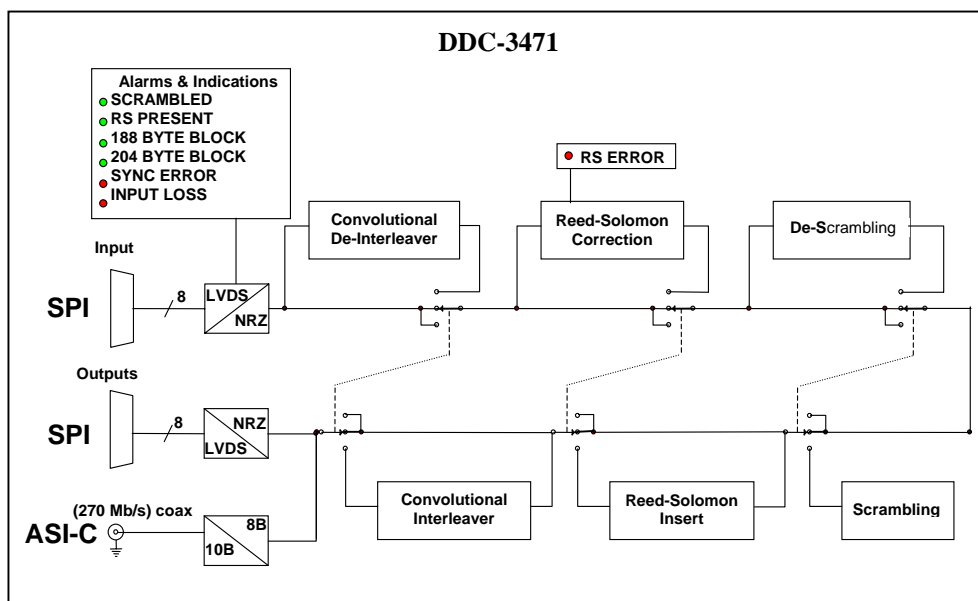
### Reed-Solomon (RS) encoder

A shortened Reed-Solomon (RS) code is applied to each randomised transport packet to generate an error-protected packet. This code is also applied to the Sync Byte itself.

### Convolutional interleaver

This part performs a depth  $I = 12$  convolutional interleaving of the error-protected packets. The periodicity of the sync Bytes remains unchanged.

## Block diagram



# DDC-3471 Technical Specifications

## Input:

Type	1 x SPI, 25 pin 'D' female connector.
Rate	2 Mb/s to 60 Mb/s

## Outputs:

Type	1 x SPI 25 pin 'D' female connector.
	1 x ASI-C 75Ω, 800 mVp-p, BNC connector.

## Alarm:

General alarm	Sync error / input loss/ power loss. 1 set N/O or 1 set N/C contacts, set by on board link. 2 pin 0.1" IDC male connector.
---------------	--

Power Requirements	28 Vac CT (14-0-14) or $\pm 16$ Vdc.
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Power consumption	<3 VA.
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## Other:

Temperature range	0 - 50° C ambient
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Mechanical	Mounts in IRT FRU-1030 1 RU 19" rack chassis with input, output and power connections on the rear panel.
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Finish:	Front panel	Grey enamel, silk-screened black lettering & red IRT logo.
	Rear assembly	Detachable silk-screened PCB with direct mount connectors to Eurocard and external signals.

Dimensions	6 HP x 3 U x 220 mm IRT Eurocard.
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Supplied accessories	Rear connector assembly including matching connector for alarm output.
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**Due to our policy of continuing development, these specifications are subject to change without notice.**

# Technical description DDC-3471

The DDC-3471 processes an SPI input and outputs processed SPI and ASI-C at the input data rate.

This module is capable of performing scrambling, de-scrambling, RS encoding, RS decoding, interleaving and de-interleaving. It can encode as well as decode different MPEG TS formats. The module is normally set up as either a decoder or an encoder. Combinations of both functions simultaneously are somewhat difficult and should be avoided.

The processing functions are selected using three switches (interleaving, RS coding and scrambling) on the front panel. Each switch has three positions (up, centre or down).

The DDC-3471 is internally divided into a decoder followed by an encoder.

A switch set to the UP position applies processing to the decoding section.

A switch set to the DOWN position applies processing to the encoding section.

A switch set to the CENTRE position does not perform that function to either the decoding or encoding section.

Applying a function to both the decoder and encoder section simultaneously is prevented by means of each switch having only three positions. Full encoding and decoding is possible by using two DDC-3471 modules connected together, if this is ever required.

In most instances the DDC-3471 would be set to decoder mode with the de-interleaver and RS decoder functions enabled.

To generate a FOXTEL compliant TS stream from a Rohde & Schwarz DVG, the DDC-3471 would be set with the interleaver and RS encoder enabled.

## SPI Output

The SPI output uses differential LVDS signalling with a standard 25 pin 'D' female connector.

The output is disabled when Input Loss Alarm is triggered.

## ASI Output

ASI operates at 270 Mbit/s and uses 8B/10B coding with K28.5 stuffing bytes. The DDC-3471 implements the data burst method of K28.5 stuffing. The ASI cable output uses a 75 Ohm BNC connector. A DVT/R-3210 optical link can be used to transport the ASI-C signal via fibre optic cable. *See DVT/R-3210 brochure or manual for further information.*

## Input Loss Alarms

The Input Loss Alarm will be asserted in the absence of SPI input clock.

## Input TS Sync Error

After 2 consecutive TS syncs are missed a TS Sync Error is deemed to have occurred. The Sync error is reset only after 5 consecutive TS syncs have been detected. The SYNC Error LED lights when a Sync error has been detected and remains lit for approximately 300 ms after the Sync error has been reset.

## 188 TS Sync length indicator

If the number of bytes between TS syncs is 188 then the 188 LED lights.

## 204 TS Sync length indicator

If the number of bytes between TS syncs is 204 then the 204 LED lights.

## Alarm relay

Alarm outputs are available on the rear assembly using the J 2 connector. N/O & N/C outputs can be selected using LK 1. The relay is triggered upon loss of input or sync error. The N/O contact is preferred as it switches upon loss of power or removal of the DDC-3471 from its rear assembly.

LED indicators 188 TS Byte length, 204 TS Byte length, CRC error, Scram present, RS present are blanked during Input loss or sync loss.

## Configuration

### Links & options:

#### Warning:

Some of the following links are for factory use only during set-up and should not be changed.

Links may be changed without disconnecting power. However, when any link is changed, normal decoding of the MPEG TS will be disturbed. The time taken before normal decoding resumes is dependent on the decoder in use and may be up to five seconds.

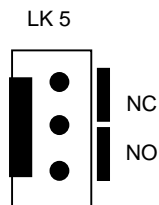
LK 1        OUT   Standard Operation.  
             IN     Sets transport stream indicator when uncorrectable RS errors are detected.

LK 2        Out     Standard Operation.  
             IN     SPI DVAL always high.

LK 3        Reserved for factory set-up.

LK 4        Reserved for factory set-up.

LK 5:       J1 Alarm relay output



# Installation

## Operational Safety:

### WARNING

Operation of electronic equipment involves the use of voltages and currents that may be dangerous to human life. Note that under certain conditions dangerous potentials may exist in some circuits when power controls are in the **OFF** position. Maintenance personnel should observe all safety regulations.

Do not make any adjustments inside equipment with power **ON** unless proper precautions are observed. All internal adjustments should only be made by suitably qualified personnel. All operational adjustments are available externally without the need for removing covers or use of extender cards.

## Pre-installation:

### Handling:

This equipment may contain or be connected to static sensitive devices and proper static free handling precautions should be observed.

Where individual circuit cards are stored, they should be placed in antistatic bags. Proper antistatic procedures should be followed when inserting or removing cards from these bags.

### Power:

AC mains supply: Ensure that operating voltage of unit and local supply voltage match and that correct rating fuse is installed for local supply.

DC supply: Ensure that the correct polarity is observed and that DC supply voltage is maintained within the operating range specified.

### Earthing:

The earth path is dependent on the type of frame selected. In every case particular care should be taken to ensure that the frame is connected to earth for safety reasons. See frame manual for details.

**Signal earth:** For safety reasons a connection is made between signal earth and chassis earth. No attempt should be made to break this connection.

## Installation in frame or chassis:

See details in separate manual for selected frame type.



## Connections:

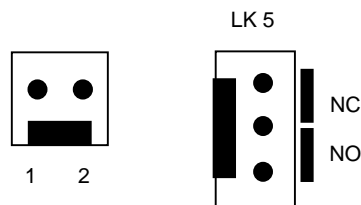
### SPI connectors:

The SPI uses 25 pin 'D' connectors. Cable connectors are male and equipment connectors are female. Interconnecting cables and connectors must be shielded. Logic levels are LVDS.

Pin	Signal line	Pin	Signal line
1	Clock A	14	Clock B
2	System Gnd	15	System Gnd
3	Data 7 A(MSB)	16	Data 7 B
4	Data 6 A	17	Data 6 B
5	Data 5 A	18	Data 5 B
6	Data 4 A	19	Data 4 B
7	Data 3 A	20	Data 3 B
8	Data 2 A	21	Data 2 B
9	Data 1 A	22	Data 1 B
10	Data 0 A	23	Data 0 B
11	DVALID A	24	DVALID B
12	PSYNC A	25	PSYNC B
13	Cable Shield		

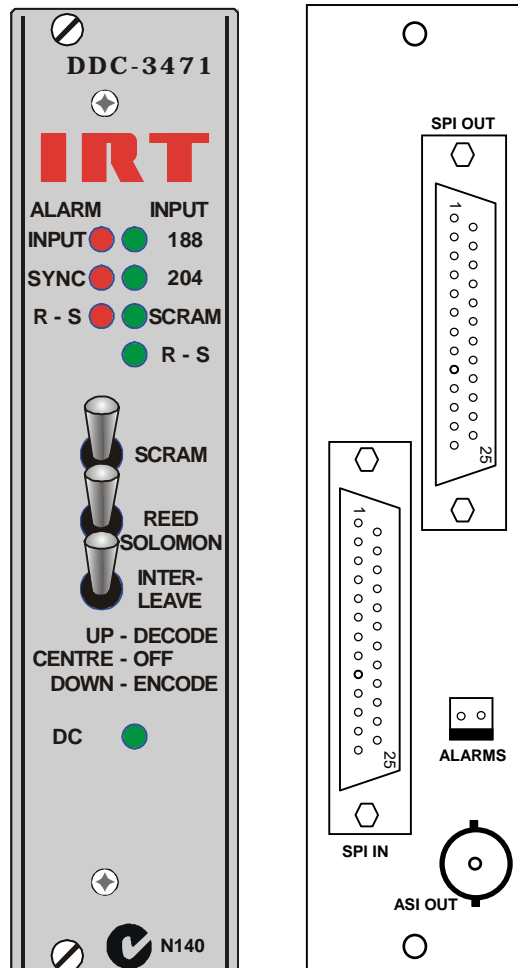
### Alarm connections:

J 1 Alarm relay output



### Front & rear panel connector diagrams

The following front panel and rear assembly drawings are not to scale and are intended to show relative positions of connectors, indicators and controls only.

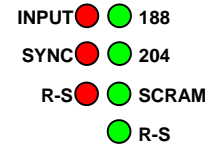


# Operation

## Front indicators:

### Input loss alarm:

This LED lights when no data transmission is detected at the input for a given time. MPEG-2 TS always contain a sync byte every 204 or 188 bytes irrespective of data content. Therefore, if 2040 or more, consecutive 1's or 0's are been detected; then the input is deemed lost.



### Sync loss alarm:

This LED lights for at least 300 ms when two or more MPEG-2 TS sync bytes are absent. The LED extinguishes when five or more correct SYNC bytes are detected.

### 188 byte indicator:

This LED lights when a valid MPEG-2 TS stream containing 188 bytes between sync bytes is detected.

### 204 byte indicator:

This LED lights when a valid MPEG-2 TS stream containing 204 bytes between sync bytes is detected.

### Scrambling presence indicator:

This LED lights when a valid MPEG-2 TS stream containing a byte sequence that corresponds to scrambling. A scrambling byte sequence uses an inverted 47H sync byte (B8H) every eighth sync to signify the start of the scrambling sequence.

### RS (Reed Solomon) presence indicator:

This LED lights when Reed Solomon error correction bytes are present in place of the 16 dummy bytes of a 204 Byte MPEG-2 TS. The DDC-3471 considers any data content other than all 0's during the 16 dummy bytes to be RS correction bytes.

## Processing controls:

This module is capable of performing scrambling, de-scrambling, RS encoding, RS decoding, interleaving and de-interleaving. It can encode or decode different MPEG TS formats.

In this context, the word scrambling refers to the process of Sync1 inversion and randomisation for the purpose of energy dispersal of the signal. It does not refer to the encryption applied to Pay TV signals to control access to particular channels or programs.

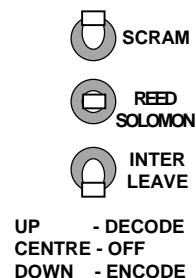
For a description of the processes involved see *Application examples - Cable Systems* and *Technical specifications - Characteristics of signal types - MPEG-2 transport layer coding*.

The module is normally set up as either a decoder or an encoder. Combinations of both functions simultaneously should be avoided.

The processing functions are selected using three switches (interleaving, RS coding and scrambling) on the front panel. Each switch has three positions (up, centre or down).

The DDC-3471 is internally divided into a decoder followed by an encoder. See *Block diagrams*.

A switch set to the UP position applies processing to the decoding section;  
a switch set to the DOWN position applies processing to the encoding section;  
and a switch set to the CENTRE position does not perform that function to either the decoding or encoding section.



Applying a function to both the decoder and encoder section simultaneously is prevented by means of each switch having only three positions. Full encoding and decoding is possible by using two DDC-3471 modules connected together, if this is ever required.

In most instances, the DDC-3471 would be set to decoder mode with the de-interleaver and RS decoder functions enabled.

## Maintenance & storage

### Maintenance:

No regular maintenance is required.

Care however should be taken to ensure that all connectors are kept clean and free from contamination of any kind. This is especially important in fibre optic equipment where cleanliness of optical connections is critical to performance.

### Storage:

If the equipment is not to be used for an extended period, it is recommended the whole unit be placed in a sealed plastic bag to prevent dust contamination. In areas of high humidity a suitably sized bag of silica gel should be included to deter corrosion.

Where individual circuit cards are stored, they should be placed in antistatic bags. Proper antistatic procedures should be followed when inserting or removing cards from these bags.

## Warranty & Service

Equipment is covered by a limited warranty period of three years from date of first delivery unless contrary conditions apply under a particular contract of supply. For situations when “**No Fault Found**” for repairs, a minimum charge of 1 hour’s labour, at IRT’s current labour charge rate, will apply, whether the equipment is within the warranty period or not.

Equipment warranty is limited to faults attributable to defects in original design or manufacture. Warranty on components shall be extended by IRT only to the extent obtainable from the component supplier.

### Equipment return:

Before arranging service, ensure that the fault is in the unit to be serviced and not in associated equipment. If possible, confirm this by substitution.

Before returning equipment contact should be made with IRT or your local agent to determine whether the equipment can be serviced in the field or should be returned for repair.

The equipment should be properly packed for return observing antistatic procedures.

The following information should accompany the unit to be returned:

1. A fault report should be included indicating the nature of the fault
2. The operating conditions under which the fault initially occurred.
3. Any additional information, which may be of assistance in fault location and remedy.
4. A contact name and telephone and fax numbers.
5. Details of payment method for items not covered by warranty.
6. Full return address.
7. For situations when “**No Fault Found**” for repairs, a minimum charge of 1 hour’s labour will apply, whether the equipment is within the warranty period or not. Contact IRT for current hourly rate.

Please note that all freight charges are the responsibility of the customer.

The equipment should be returned **to the agent who originally supplied the equipment** or, where this is not possible, to IRT direct as follows.

Equipment Service  
IRT Electronics Pty Ltd  
26 Hotham Parade  
ARTARMON  
N.S.W. 2064  
AUSTRALIA

Phone: 61 2 9439 3744  
Email: service@irtelectronics.com

Fax: 61 2 9439 7439

# Characteristics of signal types

## Coding characteristics

### G.703:

The **HDB3** (High Density Bi-polar of order 3) code as defined in G.703 for 34,368 Kbits/s is as follows:

Binary 1 bits are represented by alternate positive and negative pulses and binary 0 bits by spaces. Exceptions are made when strings of successive 0 bits occur in the binary signal.

Each block of 4 successive zeros is replaced by 000V or B00V where B is an inserted pulse of the correct polarity and V is an inserted pulse violating the polarity rule. The choice of 000V or B00V is made so that the number of B pulses between consecutive V pulses is odd so that successive V pulses are of alternate polarity and so no DC component is introduced.

The **B3ZS** (Bipolar with Three Zero Substitution) (Also designated **HDB2** - High Density Bi-polar of order 2) code as defined in G.703 for 44,736 Kbits/s is as follows:

Binary 1 bits are represented by alternate positive and negative pulses and binary 0 bits by spaces. Exceptions are made when strings of successive 0 bits occur in the binary signal.

Each block of 3 successive zeros is replaced by 00V or B0V. The choice of 00V or B0V is made so that the number of B pulses between consecutive V pulses is odd, so that successive V pulses are of alternate polarity and so no DC component is introduced.

## Synchronous Parallel Interface (SPI)

SPI is a system for parallel transmission of variable data rates. The data transfer is synchronised to the Byte clock of the MPEG transport stream.

The data to be transmitted are MPEG-2 transport packets. The data signals are synchronised to the clock depending on the transmission rate.

The parallel interface has three allowable transmission formats:

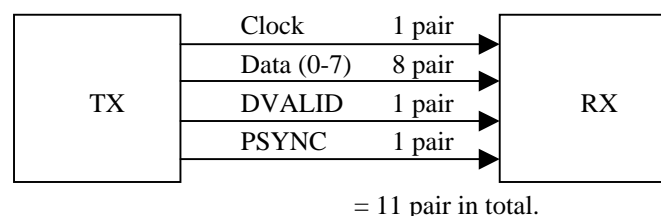
- 188 byte packets
- 204 Byte packets (188 data Bytes + 16 dummy Bytes)
- 204 byte packets (188 data Bytes + 16 additional valid Bytes)

The clock, data and synchronisation signals are transmitted in parallel. They comprise 8 data bits together with one (MPEG-2) PSYNC signal and a DVALID signal.

The DVALID signal indicates in the 204 Byte mode that the additional space is filled with dummy Bytes.

All signals are synchronous to the clock signal. The signals are coded in NRZ form.

The clock is a square wave signal where the 0-1 transition represents the data transfer time. The clock frequency depends on the transmission rate. The frequency corresponds to the useful bitrate of the MPEG2 transport layer and shall not exceed 13.5 MHz.



### Electrical characteristics of the interface

Each of the eleven line drivers (source) has a balanced output and each line receiver (destination) a balanced input employing LVDS drivers / receivers. All digital signal time intervals are measured between the half-amplitude points.

### Logic convention

A binary 1 is represented by the non-inverted output being positive with respect to the inverted output.

A binary 0 is represented by the non-inverted output being negative with respect to the inverted output.

## Asynchronous Serial Interface (ASI)

The Asynchronous Serial Interface (ASI) provides a system for serial encoded transmission of different data rates with a constant transmission rate of 270 Mbit/s.

The ASI standard supports coaxial cable and multi-mode fibre-optic cable (using LED emitters).

### ASI Protocol Architecture Description

The ASI protocol is divided into three architectural layers: Layer-0, Layer-1 and Layer-2.

MPEG Transport Packets form the top layer (Layer 2), and the bottom layers are based upon the Fibre Channel Standard (Layers 1 and 0). Layer 2 is defined using the MPEG-2 Standard ISO/IEC 13818-1 (Systems). Layers 1 and 0 are based upon a subset of ANSI Standard X3T11/ Levels FC-1 and FC-0.

### Layer-0: Physical Requirements

The physical Layer defines the transmission media, the drivers and receivers, and the transmission speeds. The physical interface provides for both LED-driven multimode fibre and copper coaxial cable.

### Line Rates and Bit Timing

The encoded line rate with the 8B/10B block code is 270 Mbit/s which results in a media transmission rate of 270 MBaud. At the transmitter, the serialisation is done using a fixed oscillator to establish this 270 MBaud rate from which a phase-locked Byte clock is derived and used to shift in parallel Bytes.

Receivers recover the serial transmission clock. A phase-locked Byte clock is derived from this recovered serial bit clock and is used to shift parallel Bytes out to Layer-1 processing elements. It is required that the encoded line rate shall be 270 MBaud  $\pm 100$  ppm.

### Layer-1 Data Encoding

The ASI Transmission Layer 1 deals with encoding/decoding aspects, which are independent of the transmission medium characteristics. The encoding method utilised is specified in the fibre channel document X3T11

At Layer-1, Bytes are 8B/10B coded, which produces one 10-bit word for each 8-bit Byte presented.

The 8B/10B transmission coding provides for both a self checking capability and Byte synchronisation of the link.

The 10B transmission code is defined in terms of "disparity": the difference in the number of "1" bits and "0" bits in the transmitted serial data stream. The disparity characteristics of the code maintain DC balance.

Special characters are defined as extra code points beyond the need to encode a Byte of data. One in particular is used to establish Byte synchronisation in the ASI transmission link.

The 10-bit words are then passed through a parallel-to-serial converter, which operates at a fixed output bit-rate of 270 Mbit/s.. If the converter requests a new input word and the data source does not have one ready, a synchronisation word is inserted. These sync words are ignored by receive equipment.

The resulting serial bit stream is passed to the output driver circuit for coaxial or fibre-optic cable.

Receive data arriving on a coaxial cable or fibre is first coupled to a circuit, which recovers clock and data.

Recovered serial data bits are passed to a 10B/8B decoder that converts the 10-bit transmission words back into the 8-bit Bytes originally transmitted. In order to recover Byte alignment, the 10B/8B decoder initially searches for synchronisation words. Once found, the start of the synchronisation word marks the boundary of subsequent received data words and establishes proper Byte-alignment of decoder output Bytes.

**NOTE - The ASI coding is sensitive to logical inversion of the transmitted bits. Therefore, to ensure correct operation, care must be taken that equipment interface circuitry of the non-inverting type is used.**

The **Bit-Error-Rate (BER) Performance** shall be less than one part in  $10^{13}$ .

### Layer-2 Transport Protocol

The ASI Transmission Layer-2 standard uses the MPEG-2 Transport Stream Packet as defined in ISO/IEC 13818-1 (Systems) as its basic message unit. Optionally the RS coded Byte structure as specified in ETS 300 429 is also supported.

Data to be transmitted are presented in Byte-synchronised form as MPEG-2 Transport packets. Transport Packets may be presented to Layer-2 either as a burst of contiguous Bytes, or as individual Bytes spread out in time.

The ASI Interface Layer-2 definition employs the MPEG-2 Transport Stream packet syntax with the additional requirement that every Transport Packet shall be preceded with at least two synchronisation characters. This allows re-sync within one transport packet in the event that a line disturbance causes loss of sync.

## MPEG-2 transport layer coding

The MPEG-2 Transport Layer is defined in ISO/IEC DIS 13818-1 [1]. The Transport Layer for MPEG-2 data is comprised of packets having 188 Bytes, with one Byte for synchronisation purposes, three Bytes of header containing service identification, scrambling and control information, followed by 184 Bytes of MPEG-2 or auxiliary data.

The framing organisation is based on the MPEG-2 transport packet structure.

### Channel coding

To achieve the appropriate level of error protection required for cable transmission of digital data, a FEC based on Reed-Solomon encoding is used. In contrast to the Baseline System for satellite described in ETS 300 421, no convolutional coding is applied to cable transmission. Protection against burst errors is achieved by the use of Byte interleaving.

### Randomisation for spectrum shaping (Scrambling)

The System input stream is organised in fixed length packets (see figure 2), following the MPEG-2 transport multiplexer. The total packet length of the MPEG-2 transport MUX packet is 188 Bytes. This includes 1 sync-word Byte (i.e. 47<sub>HEX</sub>). The processing order at the transmitting side shall always start from the MSB (i.e. 0) of the sync word-Byte (i.e. 01000111).

In order to comply with the System for satellite, (see ETS 300 421) and to ensure adequate binary transitions for clock recovery, the data at the output of the MPEG-2 transport multiplex is randomised.

The polynomial for the Pseudo Random Binary Sequence (PRBS) generator is:

$$1 + X^{14} + X^{15}$$

Loading of the sequence 100101010000000" into the PRBS registers, is initiated at the start of every eight transport packets. To provide an initialisation signal for the de-scrambler, the MPEG-2 sync Byte of the first transport packet in a group of eight packets is bitwise inverted from 47<sub>HEX</sub> to B8<sub>HEX</sub>.

The first bit at the output of the PRBS generator is applied to the first bit of the first Byte following the inverted MPEG-2 sync Byte (i.e. B8<sub>HEX</sub>). To aid other synchronisation functions, during the MPEG-2 sync Bytes of the subsequent 7 transport packets, the PRBS generation continues, but its output is disabled, leaving these Bytes unrandomised. The period of the PRBS sequence shall therefore be 1,503 Bytes.

The randomisation process is active also when the modulator input bit-stream is non-existent, or when it is non-compliant with the MPEG-2 transport stream format (i.e. 1 sync Byte + 187 packet Bytes). This is to avoid the emission of an unmodulated carrier from the modulator.

### Reed-Solomon coding

Following the energy dispersal randomisation process, systematic shortened Reed-Solomon encoding is performed on each randomised MPEG-2 transport packet, with T = 8. This means that 8 erroneous Bytes per transport packet can be corrected. This process adds 16 parity Bytes to the MPEG-2 transport packet to give a codeword (204, 188).

NOTE: RS coding is applied also to the packet sync Byte, either non-inverted (i.e. 47<sub>HEX</sub>) or inverted (i.e. B8<sub>HEX</sub>).

Code Generator Polynomial:  $g(x) = (x + \lambda^0)(x + \lambda^1)(x + \lambda^2) \dots (x + \lambda^{15})$ , where  $\lambda = 02_{\text{HEX}}$

Field Generator Polynomial:  $p(x) = x^8 + x^4 + x^3 + x^2 + 1$

The shortened Reed-Solomon code is implemented by appending 51 Bytes, all set to zero, before the information Bytes at the input of a (255, 239) encoder; after the coding procedure these Bytes are discarded.

**Convolutional interleaving**

Convolutional interleaving with depth  $I = 12$  is applied to the error protected packets (see figure 2c). This results in an interleaved frame.

The convolutional interleaving process is based on the Forney approach which is compatible with the Ramsey type III approach, with  $I = 12$ . The Interleaved Frame is composed of overlapping error-protected packets and is delimited by MPEG-2 sync Bytes (preserving the periodicity of 204 Bytes).

The interleaver may be composed of  $I = 12$  branches, cyclically connected to the input Byte-stream by the input switch. Each branch is a First In First Out (FIFO) shift register, with depth  $(Mj)$  cells (where  $M = 17 = N/I$ ,  $N = 204 =$  error protected frame length,  $I = 12 =$  interleaving depth,  $=$  branch index). The cells of the FIFO shall contain 1 Byte, and the input and output switches is synchronised.

For synchronisation purposes, the sync Bytes and the inverted sync Bytes are always routed into the branch "0" of the interleaver (corresponding to a null delay).

The de-interleaver is similar, in principle, to the interleaver, but the branch indexes are reversed (i.e.  $j = 0$  corresponds to the largest delay). The de-interleaver synchronisation can be carried out by routing the first recognised sync Byte into the "0" branch.

## Electrical characteristics:

### Electrical characteristics CCITT G.703 2048 Kb/s:

Pair each direction	One coaxial pair.
Test load impedance	75 $\Omega$ resistive.
Signal level	2.37 V.
Nominal pulse width	244 ns.
Code conversion	HDB3.
Pulse shape	Fig. 15/G.703.
Jitter at input port	§ 3 of recommendation G.823.
Jitter at output port	§ 2 of recommendation G.823.
Return loss at input ports:	
51 KHz to 102 KHz	12 dB
102 KHz to 2048 KHz	18 dB
2048 KHz to 3072 KHz	14 dB

### Electrical characteristics CCITT G.703 8448 Kb/s:

Pair each direction	One coaxial pair
Test load impedance	75 $\Omega$ resistive
Signal level	2.37 V
Nominal pulse width	59 ns
Code conversion	HDB3
Pulse shape	Fig. 16/G.703
Jitter at input port	§ 3 of recommendation G.823
Jitter at output port	§ 2 of recommendation G.823
Return loss at input ports:	
211 KHz to 422 KHz	12 dB
422 KHz to 8448 KHz	18 dB
8448 KHz to 12672 KHz	14 dB

### Electrical characteristics CCITT G.703 34368 Kb/s:

Cable type	Coaxial.
Impedance	75 $\Omega$
Signal level	1.0 V
Nominal pulse width	14.55 ns
Code conversion	HDB3
Pulse shape	Fig. 17/G.703
Jitter at input port	§ 3 of recommendation G.823
Jitter at output port	§ 2 of recommendation G.823
Return loss at input ports:	
860 KHz to 1720 KHz	>12 dB
1720 KHz to 34368 KHz	>18 dB
34368 KHz to 51550 KHz	>14 dB

### Electrical characteristics CCITT G.703 Shaped 44736 Kb/s:

Cable type	Coaxial.
Impedance	75 $\Omega$
Signal level	
Power at 22368 KHz	+1.8 dBm to +5.7 dBm.
Power at 44736 KHz	>20 dBm below power at 22368 KHz.
Code conversion	B3ZS
Pulse shape	Fig. 14/G.703

### Electrical characteristics CCITT G.703 Unshaped 44736 Kb/s:

Cable type	Coaxial.
Impedance	75 $\Omega$
Signal level	1.0 V
Nominal pulse width	14.55 ns
Code conversion	B3ZS
Pulse shape	Fig. 17/G.703
Jitter at input port	§ 3 of recommendation G.823
Jitter at output port	§ 2 of recommendation G.823
Return loss at input ports:	
860 KHz to 1720 KHz	>12 dB
1720 KHz to 34368 KHz	>18 dB
34368 KHz to 51550 KHz	>14 dB



## Electrical characteristics SPI:

### Line Driver Characteristics (Source)

Output impedance	100 $\Omega$ maximum
Common mode voltage	1.125 V to 1.375 V
Signal amplitude	247 mV to 454 mV
Rise and fall times	< T/7, measured between the 20% and 80% amplitude points, with a 100 $\Omega$ resistive load. The difference between rise and fall times shall not exceed T/20.

### Line Receiver Characteristics (Destination)

Input impedance	90 $\Omega$ to 132 $\Omega$
Maximum input signal	2.0 Vp-p
Minimum input signal	100 mVp-p

## General Information on DVB-ASI

For transport, the 270 Mb/s stream may be fed through DA's and switchers without regard for the underlying data rate, thus simplifying system design.

Note that the ASI signal is polarity sensitive. Although most 270 Mb/s SDI DA's and switchers will pass ASI signals, the line drivers used usually have both inverted and non-inverted outputs. For ASI, only those outputs that are non-inverted may be used.

## Electrical characteristics ASI:

### Transmitter output characteristics:

Output voltage	800 mVp-p $\pm$ 10%.
Deterministic jitter	<10% p-p.
Random jitter	<8% p-p.
Rise/fall time (20-80%)	<1.2 ns.

### Receiver input characteristics:

Minimum sensitivity (D21.5 idle pattern)	200 mV
Maximum input voltage	880 mVp-p
$s_{11}$ (range: 0.1 to 1.0 x bit rate)	-17 dB
Minimum discrete connector return loss	15 dB (5 MHz - 270 MHz)

### Coaxial link:

Impedance	75 Ohm
Equipment connector	BNC female

(Electrical measurements made with 75 Ohm resistive termination.)

## References

ANSI Standard X3T1 1/ Levels FC-1 and FC-0.

DVB-PI-232 TM1449 Interfaces for CATV/SMATV Headends & similar Professional Equipment.

ETS 300 421. Digital broadcasting systems for Television, sound and data services; framing structure, channel coding for 11/12 GHz satellite services.

ETS 300 429. Digital broadcasting systems for Television, sound and data services; framing structure, channel coding and modulation for cable systems.

ETS 300 473. Digital broadcasting systems for Television, sound and data services; Satellite Master Antenna Television (SMATV) distribution systems.

ISO/IEC 13818-1 (Systems). MPEG-2 Standard.

ITU-T Rec. G.703.

TM 1664 Rev 2 - DVB Interfaces for PDH Networks.

## Glossary of terms

8B/10B	Eight to Ten Bit Conversion.
ASI	Asynchronous Serial Interface.
ASI-C	ASI Coaxial cable.
ASI-O	ASI Fibre optic cable.
B3ZS	Bipolar with Three Zero Substitution.
BB	Baseband.
BER	Bit Error Rate.
CCIR	Comite Consultatif International des Radiocommunications.
CCITT	Comite Consultatif International Telephonique et Telegraphique.
CPLD	Custom Programmable Logic Device.
DJ	Deterministic Jitter.
DTVC	Digital Television by Cable.
DVB	Digital Video Broadcasting.
DVG	Digital Video Generator.
EBU	European Broadcasting Union.
EBU	European Broadcasting Union.
ETS	European Telecommunication Standard.
ETSI	European Telecommunications Standards Institute.
FEC	Forward Error Correction.
FIFO	First In First Out.
FPGA	Field Programmable Gate Array.
G.703	ITU CCITT recommendation G.703.
HDB3	High Density Bi-polar of order 3.
IF	Intermediate Frequency.
IRD	Integrated Receiver Decoder.
ITU	International Telecommunications Union.
LSB	Least Significant Bit.
LVDS	Low Voltage Differential Signalling.
Mb/s	Megabits per second.
MPEG	Moving Pictures Experts Group.
MPEG	Motion Picture Experts Group.
MSB	Most Significant Bit.
MSB	Most Significant Bit.
MUX	Multiplex.
NO	Normally open contact set.
NC	Normally closed contact set.
NRZ	Non Return to Zero.
PDH	Plesiochronic Digital Hierarchy.
PRBS	Pseudo Random Binary Sequence.
QAM	Quadrature Amplitude Modulation.
QEF	Quasi Error Free.
QPSK	Quarternary Phase Shift Keying.
R & S	Rohde & Schwarz.
RF	Radio Frequency.
RJ	Random Jitter.
RS	Reed Solomon.
SDI	Serial Digital Interface.
SMATV	Satellite Master Antenna Television.
SPI	Synchronous Parallel Interface MPEG2.
SSI	Synchronous Serial Interface.
TDM	Time Division Multiplex.
TS	Transport Stream.
TV	Television.

## Drawing index

Drawing #	Sheet #	Description
804489	1	DDC-3471 circuit schematic
804489	2	DDC-3471 circuit schematic
804489	3	DDC-3471 circuit schematic

